

A Video Denoising Method with 3D Surfacelet Transform Based on Block matching and Grouping

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Abstract—This paper proposes a novel video denoising method combining block matching based on the E3SS and grouping these blok strategy, 3D Surfacelet transform. Firstly, we utilize the SAD standard and E3SS search algorithm which we proposed by searching all frames for blocks which are similar to the currently processed one. Secondly, the matched blocks are stacked together to form some new 3D Sub-video sequence and because of the similarity between them, the data in the video array exists high level of correlation. We apply the 3D surfacelet transform to them and effectively attenuate the noise by solid threshold shrinkage of the 3D transform coefficients. Finally, inversely transforming the coefficients and obtaining the denoising video. This algorithm is obviously better than other 3D method in the denoising effect and the PSNR is increased about 0.9 dB. In terms of visual quality, the proposed method can effectively preserve the video detail, and the trajectory of motion object is very smooth, which is especially adequate to process the video flames with acute movement and plenty of large area movement object and background movement.

Index Terms—video denoising;Surfacelet transform;Block matching;Grouping

I. INTRODUCTION

The traditional wavelet denoising is usually each frame denoising, without considering the correlation between each frame movement, moving objects trailing phenomenon. [1] A new video denoising algorithm is the video signal as a special 3d signal, three-dimensional transform to regard it as a whole, the algorithm is effective

to solve the moving object trailing, flashing and algorithm robustness problems. The method of [2-4] using 3D double tree complex wavelet (3DTCWT) to decompose signal to six directions, has good selectivity, but when the movement in video are very intense, the video texture is very much, its directions are obviously insufficient. The proposed 3D Curvelet^[5-8] like the 3D TCWT method. Yue Lu of Surfacelet Transform^[9-13] (ST) is a new kind of 3D transformation, has many direction decomposition, anisotropy, the efficiency of the tree structure filter, completely rebuilding and low redundancy properties, which is very suitable for video processing. Xiao in [11] proposed the 3DCMST method that the ST coefficient matrix is divided into several parts using 3D context model in the threshold value selection according to the energy, but without considering the original video frame correlation, no motion detection and motion estimation, and so has great redundancy, especially for the high correlation between frames.

This paper presents a BMG-3DST (Block-matching Grouping 3D surfacelet transform) Video denoising algorithm. Firstly, using SAD standards and E3SS search algorithm, the motion estimation, motion detection and interframe block matching are made between the video frames. Secondly, group the matched bocks from the video into some groups which are new 3D subsequence. Adopting Surfacelet transform on the new 3D subsequence and filtering the surfacelet transform coefficients using the hard threshold. Finally, inverse surfacelet transform the filtered coefficients to the 3D subsequence. And restore the 3D subsequence to original video. Experiments show that this method can achieve better visual effect and PSNR. Especially, the method is suitable for high correlation between neighboring frames of the video, such as the object image containing acuteness movement video.

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II. BLOCK MATCHING AND GROUPING

Video sequence exists the space redundancy and temporal redundancies. The motion estimation can effectively eliminate motion video frame exists between the temporal redundancies. The video compression standard such as MPEG1/24, h.261, h.263 h.264^[14-18] are base on block matching motion estimation algorithm.

Block matching criterion

Block matching algorithm of matching effect depends on the search mode, matching criterion, etc. Matching criterion refers to the cost function, motion estimation for that cost function is the smallest reference image block relative to the current image block of displacement, the displacement is sports vector. For the same image block, different matching criterion may have different motion vector, decoding the image quality will also have a difference. Commonly block matching criterion including MSE, MAD, and MSE etc. My method uses the least mean-square error (SAD) as the Block matching criterion.

$$SAD(m,n) = \sum_{i=0}^{N-1} \sum_{j=0}^{N-1} f_c(i,j) - f_r(i+m,j+n) \quad (1)$$

$f_r(i,j)$ is pixel value in the reference block. $f_c(i,j)$ is the pixels of the current block. The size of the block matching is $N * N$. m and n represents the search step of the block. The best motion vector is the m and n which make the smallest SAD.

Block matching algorithm

This paper uses a kind of effective three-step search algorithm (effective three step search, E3SS). Figure 1 is the E3SS search templates, Search window size is 5 pixels. That is that the search range is $(i \pm 5, j \pm 5)$.

In the real video sequences, the distribution of the motion vectors has the characteristics of migration center. The search algorithm (FS) match results show that the matching point in the center of has the highest probability. The posterior highest probability exits the center around the top, bottom, left and right of the four neighbors^[14-16],Therefore in search of the window of a small we used a small diamond search template to replace the little square search template of the N3SS.

Firstly, searching the 13 detection points on the template. If they are the minimum block distortion (the smallest SAD), the algorithm stops the searching.

Secondly, if the MBD exists the four neighboring points in the center, Moving the diamond template to the MBD point in the first step and Continuing to search for the other points in the little diamond template until the MBD is the center of the diamond or the diamond template reaches the edge of search window. Such as showing in the figure 2, the point of (0,-1)is the MBD point in the step 1 and in the Sep 2 and locates at the center of search window. The number of the each point show that the check points in the different search stages.

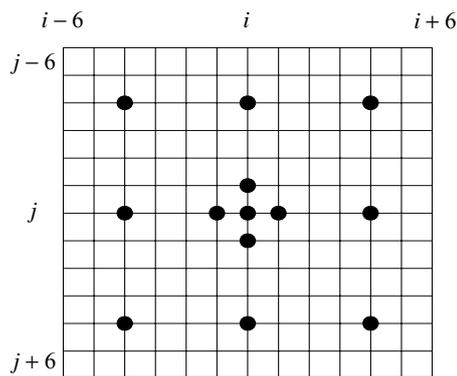


Figure 1. The E3SS search

Finally, if the MBD point is one of the eight points in the 9x9 template, the searching method uses the 3SS. The 3SS method is as following:

Halving the step length and moving the center point to the above step MBD point, block-matching the eight points at around step distance until the searching step distance is one step. The position of the last point is the best motion vector. As shown in figure 2, the point of (4,4) is the MBD point in the Step 1, then the step 2 is round the center of (4,4) which the search radius is halved to 2 pixels. Finally, Step 3 is executed based on the current MBD point (2,6) and the best matching point is found.

Grouping

According to block matching algorithm and the matching principle in the section II.B, the grouping is method finding the image blocks satisfying matching criterion from the reference frames and the rest frame in the video sequences $V(x,y,t)$ and stacking these matching blocks into a new group stored into a new 3D matrix $G_L(i, j, k)$. L is the number of group. In a sense, the $G_L(i, j, k)$ is a video sequence and suitable for 3D Surfacelet transform (ST). Figure 3 is the Schematic diagram for block matching in a frame. Block matching grouping between frames are similar and the description method is omitted because of the limited length.

III. SURFACELET

3D-DFB

In 1992, Bamberger and Smith proposed firstly the DFB (Directional Filter Bank). DFB is a non redundant transformations, can achieve the complete reconstruction the signal. In 2002, M.N.Do and M.Vetterli proposed the Contourlet transform to obtain a multi-directional and multiresolution method of sparse image in combination on the basis of the pyramidal decomposition and the DFB. The 2D-DFB frequency decomposition is as following in figure 4 (a). Yue Lu and M.N.Do in 2007 expanded the 2D-DFB to 3D and puts forward a new 3d direction filter 3D-DFB (three Dimension Directional Filter Bank s). The 3D-DFB frequency division is as in Figure 4 (b).

Multiscale Decomposition

The multidimensional surface singular of signal can be captured by the 3D-DFB frequency decomposition. Because the 3D-DFB only processes the high frequency part of signal, therefore in the use of 3D-DFB signal, signal must be decomposed by multi-scale. A new Surfacelet transformation is constituted by Combining multi-scale decomposition and the 3D-DFB. In ST transform, multi-scale decomposition adopted a pyramid structure as shown in figure 5 and figure 6.

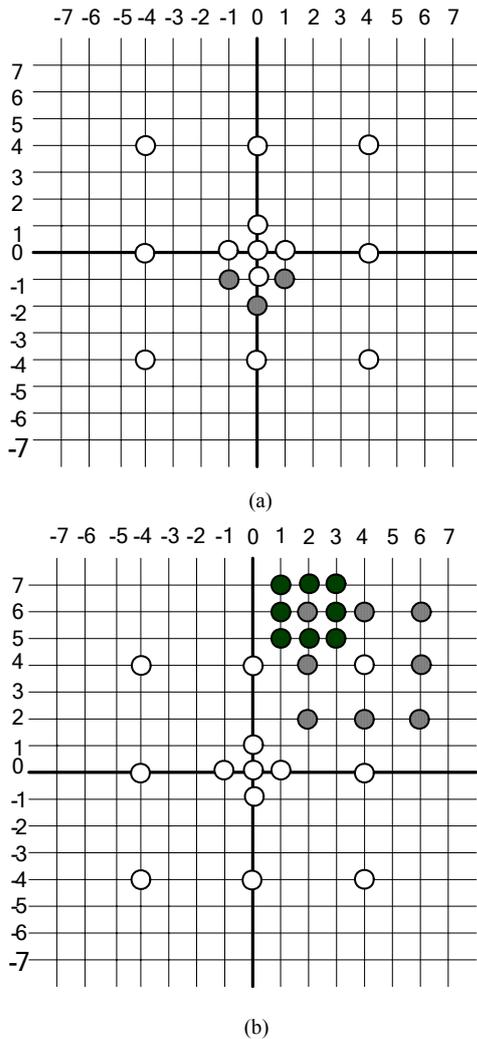


Figure 2. The E3SS search process (The hollow points are searching points in the first step, Gray points are searching points the second step.The Black points are searching points the third step.)

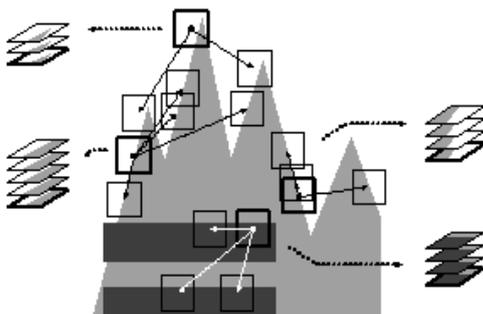


Figure 3. Grouping only in a frame diagram

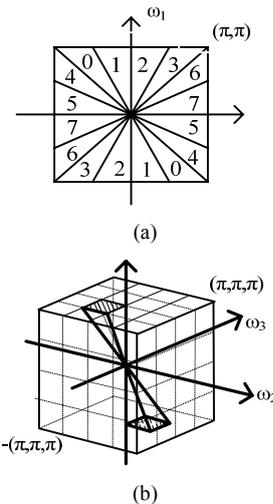


Figure 4. 2D-DFB and 3D-DFB frequency decomposition ((a) 2D-DFB Frequency decomposition (b) 3D-DFB Frequency decomposition)

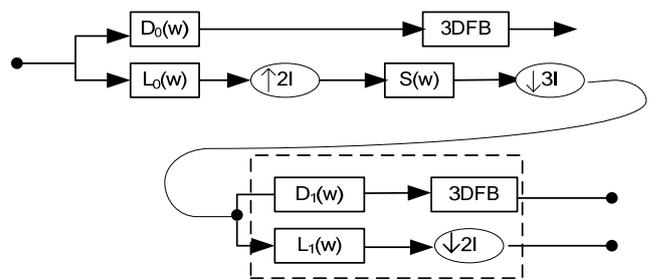


Figure 5. The block diagram of the proposed surfacelet transform.(The forward transform 3DFB) .

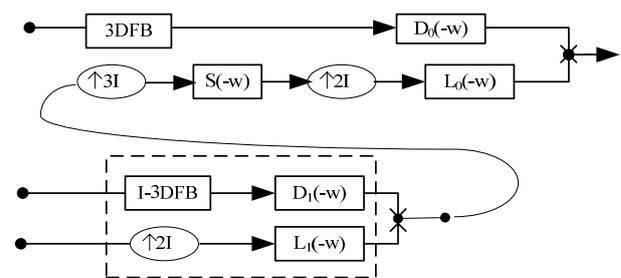


Figure 6. The block diagram of the proposed inverse surfacelet transform (its inverse I-3DFB are attached to the highpass) .

ST has the characteristics of directional decomposition, the more efficient tree filter banks, completely reconstruction and low redundancy. It can use different scale and different frequency direction sub-block accurately to capture the surface singularity of a 3D signal. The ST coefficient energy is very concentrated. Detailed description can be seeing in [9] and [11].

IV. ALGORITHM

Algorithm is listed below:

- Using SAD standards, E3SS search algorithm, and block-matching in the frame and in the adjoining frames;

- Stacking the matched blocks into a new group (the sub-video) until all blocks in the reference frame are matched;
- Executing the ST on the every noisy groups(the sub-video);
- ST coefficient using hard threshold denoising;
- Reconstruction the groups from the denoised ST coefficients;
- According to the steps 1 restoring the every block matched in the every group to its initial position in the video.

V. ANALYSIS OF EXPERIMENTAL RESULTS

Our experiment is based on Matlab 2008a and the 2GB memory, and uses the MAT formats video sequences of the size of 240×320×60 such as the Bus and Flower sequence with large background changes and the Football sequence with acute movement.

Firstly, adding the variance (30 and 50) Gaussian white noise with zero mean to the video sequences. Secondly, denoising the noisy sequences by the method such as the dual-tree complex wavelet transform (DTCWT), the Surfacelet Transform [10] with hard threshold, the 3DCMST proposed in paper [11] and our proposed method based on block-matching grouping denoising with Surfacelet Transform (BMG-3DST).In the experiment, all method is executed by decomposing the video sequence into three levels.

To investigate the effect by the decomposition layers in our algorithm, applying three layers decomposition of ST. corresponding to the number of 3D-DFB direction respectively are 64, 16, 4, shrinkage only used on the two finest levels coefficients.

Table 1 gives PSNR after denoising by the four algorithms. Figure 7 are the comparison of the football video denoising result by the four algorithms.

TABLE I.
THE PSNR(dB) OF DIFFERENT METHOD

	Flower		Football		Bus	
	30	50	30	50	30	50
Variance	30	50	30	50	30	50
DTCWT	24.60	22.59	23.67	20.90	23.60	21.59
ST	25.89	23.21	24.98	21.98	24.61	21.95
3DCMST	26.48	23.92	26.31	23.51	25.66	22.12
BM-3DST	27.27	24.87	27.19	24.52	26.45	23.95

From the experiment results can be obtained in the following conclusions:

- The PSNR of algorithm is obviously superior to the other three algorithms. This algorithm can improve the PSNR than other algorithms about 0.9dB.
- The visual effect of subjective evaluation is better than other algorithms. The denoising effect is apparently better when this algorithm used to deal with video containing acuteness movement.

We innovatively propose the video denoising algorithm based on block matching grouping and Surfacelet transform.

This algorithm can significantly improve the denoising video PSNR.

Not only can keep well the video details, and attain very good effect for movement video especially for the strenuous movement objects and the large area changes in the background. The movement objects are very fluent and does not exist the phenomenon such as flash and ghosting in the traditional algorithm.

We will focus on the next research work such as researching the more suitable block matching algorithm, adopting the different characteristics of filter for the grouping of block matching using the block-matching ST denoising to the image.

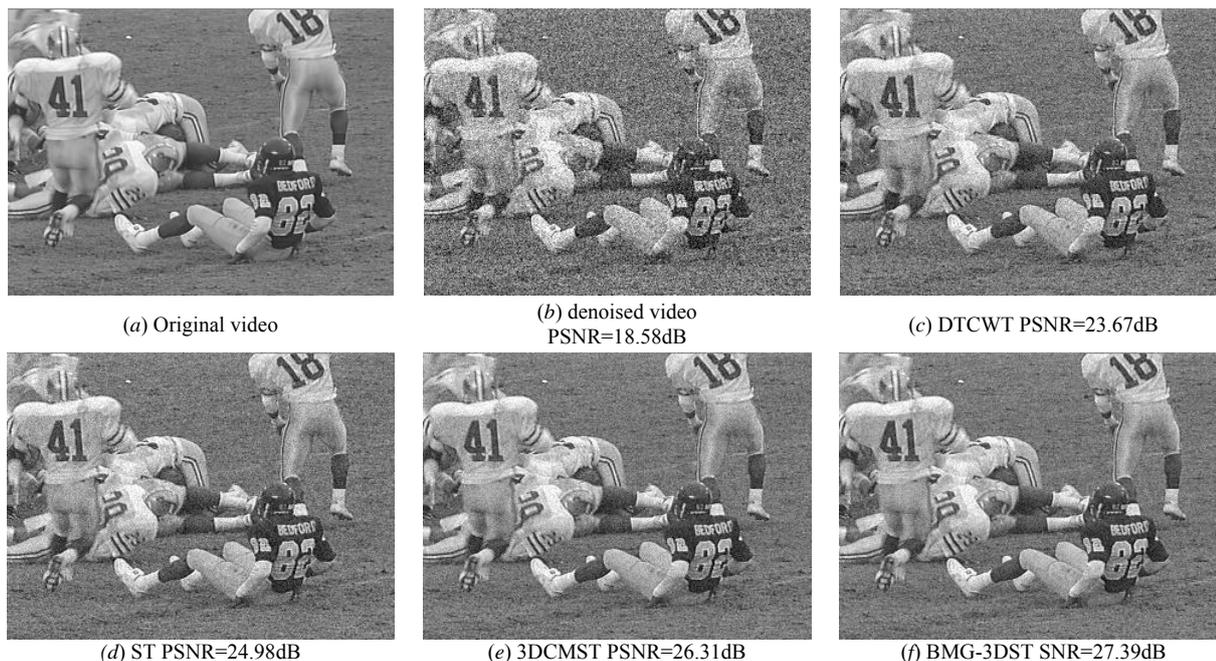


Figure 7. Effect of the denoised football video

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